

ATD 2A A 4 Y 7

Through hollow shaft ø10 to ø14 mm

Optical single- or multiturn encoders with analog output

Overview

- Encoder multiturn / analog output
- Voltage output or current output
- Control inputs reset and rotating direction
- Optical sensing singleturn, magnetical sensing multiturn
- Self-diagnostic
- Total resolution: 16 bit
- Factory-set adjustable angle (0°-360° resp. up to 16 x 360°)
- Flange connector radial



Technical data

Technical data - electrical ratings

| | |
|-----------------------------|---|
| Voltage supply | +UB= 12...30 VDC (IS-/US-version) |
| Reverse polarity protection | Yes |
| Consumption w/o load | ≤50 mA (24 VDC) |
| Interface | Analog (4...20 mA or 0...10 V) |
| Load resistor | ≥1 kΩ (recommended 10 kΩ) / voltage output ≤500 Ω (recommended 470 Ω) / current output |
| Function | Singleturn Multiturn |
| Measuring range | 90°, 180°, 360° 2, 4, 8, 16 revolutions |
| Resolution | 16 bit |
| Steps per revolution | 16384 / 14 bit |
| Number of revolutions | 16 / 4 bit |
| Sensing method | Optical (singleturn) Magnetical (multiturn) |
| Updating values | ≤130 µs |
| Code sequence | CW: ascending values with clockwise sense of rotation; looking at mounting surface |
| Output stages | Voltage output (short-circuit proof) Current output (short-circuit proof) |

Technical data - electrical ratings

| | |
|---|---|
| Interference immunity | DIN EN 61000-6-2 |
| Emitted interference | DIN EN 61000-6-3 |
| Technical data - mechanical design | |
| Size (flange) | ø58 mm |
| Shaft type | ø10 mm (through hollow shaft) ø12 mm (through hollow shaft) ø14 mm (through hollow shaft) |
| Protection DIN EN 60529 | IP 65 |
| Operating speed | ≤8000 rpm (mechanical) ≤6000 rpm (electric) |
| Starting torque | ≤0,02 Nm (+20 °C) |
| Material | Housing: aluminium Shaft: stainless steel |
| Operating temperature | -20...+85 °C |
| Relative humidity | 90 % non-condensing |
| Resistance | DIN EN 60068-2-6 Vibration 10 g, 55-2000 Hz DIN EN 60068-2-27 Shock 30 g, 11 ms |
| Weight approx. | 325 g |
| Connection | Connector M23 type 2, 12-pin |
| Mounting kit | 002 |

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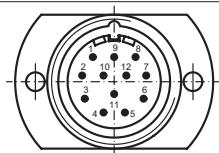
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Terminal assignment

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| Connector | Assignment |
|-----------|---|
| Pin 1 | NC |
| Pin 2 | NC |
| Pin 3 | NC |
| Pin 4 | GND _{OUT} |
| Pin 5 | U _{OUT} resp. I _{OUT} |
| Pin 6 | NC |
| Pin 7 | reset |
| Pin 8 | V/R |
| Pin 9 | error |
| Pin 10 | GND |
| Pin 11 | NC |
| Pin 12 | +UB |



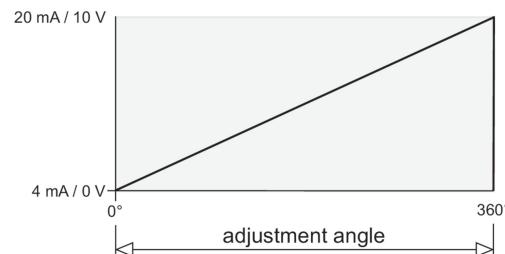
Terminal significance

| | |
|--------------------|--|
| +UB | Encoder supply voltage. |
| GND | Encoder ground connection relating to UB. |
| U _{OUT} | Voltage output increasing at clockwise rotation when looking at the mounting side. |
| I _{OUT} | Current output increasing at clockwise rotation when looking at the mounting side. |
| GND _{OUT} | Reference voltage for analogue output. |
| Reset | Reset input for setting zero position value at any desired point within the entire resolution. The resetting process is triggered by apply of UB. |
| V/R | V/R counting direction input. This input is standard on High. V/R means increasing values with clockwise shaft rotation when looking at the mounting side. V/R-Low means decreasing values with clockwise shaft rotation when looking at the mounting side. |
| Error | Diagnostic output (Open Collector with internal 10 kΩ pullup-resistor). The output is low-active, that means if no fault submitted, the output is +UB. |

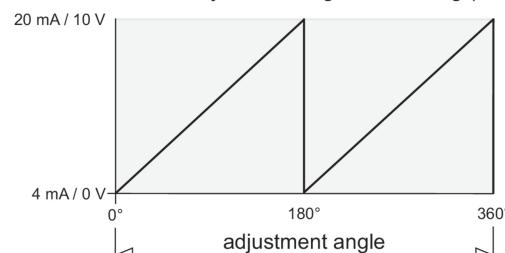
Output signals

Unipolar Output (IS-/US-version)

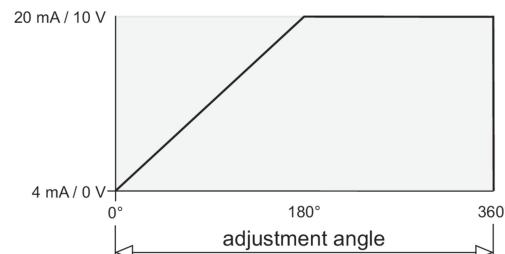
360° mech. adjustment angle, alternating (360A)



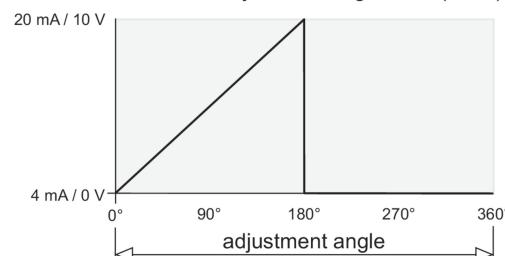
180° mech. adjustment angle, alternating (180A)



180° mech. adjustment angle, High (180H)



180° mech. adjustment angle, Low (180L)



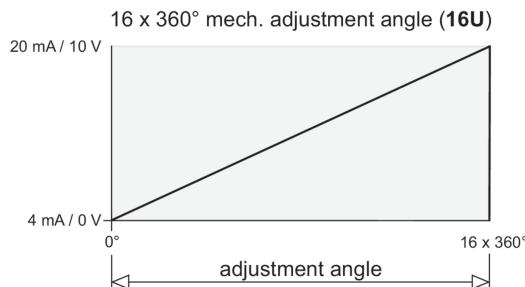
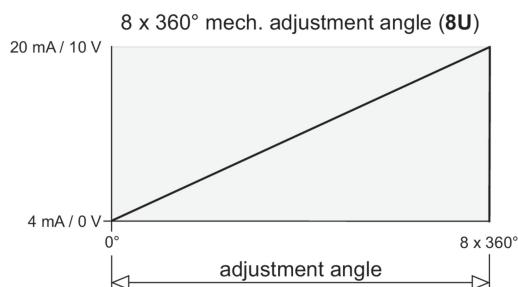
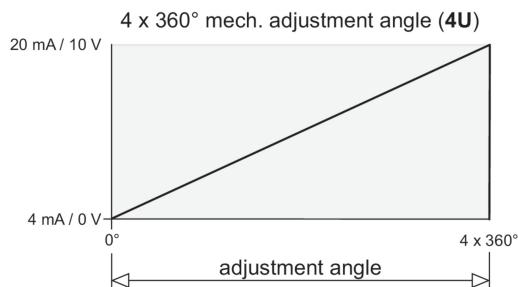
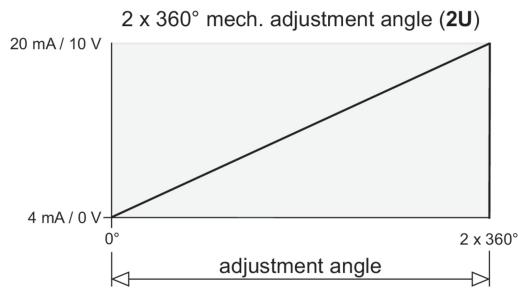
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Output signals

Unipolar Output (IS-/US-version)



Trigger level

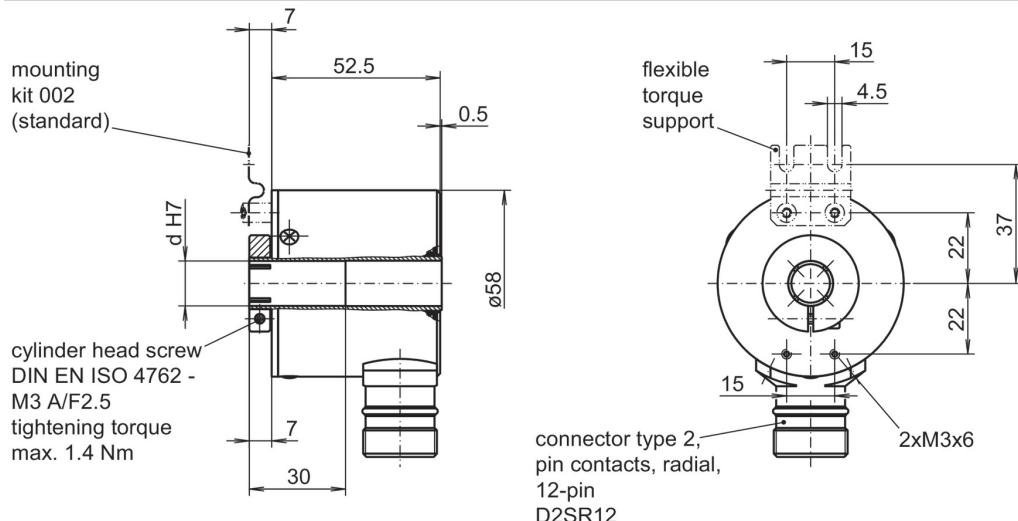
| Control input | Input circuit |
|--------------------|--|
| Input level High | $\geq 0,7$ UB |
| Input level Low | $\leq 0,3$ UB |
| Input resistance | 10 k Ω |
| Diagnostic outputs | Output circuit |
| Output level | Open Collector with internal 10 k Ω PullUp-resistance |

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Dimensions



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Ordering reference

| | ATD 2A A 4 Y 7 | #### | ## | D2SR12 | S | # | IP65 | 002 |
|--|----------------|------|----|--------|------|----|--------|-----|
| Product | ATD 2A A 4 Y 7 | | | | | | | |
| Resolution | | | | | | | | |
| 360° mech. adjustment angle, alternating (singleturn) | | | | | 360A | | | |
| 180° mech. adjustment angle, alternating (singleturn) | | | | | 180A | | | |
| 180° mech. adjustment angle, High (singleturn) | | | | | 180H | | | |
| 180° mech. adjustment angle, Low (singleturn) | | | | | 180L | | | |
| 2 x 360° mech. adjustment angle (multiturn) | | | | | 2U | | | |
| 4 x 360° mech. adjustment angle (multiturn) | | | | | 4U | | | |
| 8 x 360° mech. adjustment angle (multiturn) | | | | | 8U | | | |
| 16 x 360° mech. adjustment angle (multiturn) | | | | | 16U | | | |
| Interface | | | | | | | | |
| Current output, standard, 4...20 mA, Vin = 12...30 VDC | | | | | | IS | | |
| Voltage output, standard, 0...+10 VDC, Vin = 12...30 VDC | | | | | | US | | |
| Connection | | | | | | | D2SR12 | |
| Flange connector type 2, pin contacts, radial, 12-pin | | | | | | | | |
| Operating temperature | | | | | | | S | |
| -20...+85 °C | | | | | | | | |
| Through hollow shaft | | | | | | | | |
| ø10 mm | | | | | | 10 | | |
| ø12 mm | | | | | | 12 | | |
| ø14 mm | | | | | | 14 | | |
| Protection | | | | | | | | |
| IP 65 | | | | | | | IP65 | |
| Mounting kit | | | | | | | | |
| Mounting kit 002 | | | | | | | | 002 |

Other adjustment on request.